



Attorney Docket No: IMMR-005/00US

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PATENT

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

In re application of Kollin Tierling

Serial No.: 09/957,004

Examiner: Unassigned

Confirmation No: 2443

Art Unit: 2661

Filed: September 19, 2001

For: **CIRCUIT AND METHOD FOR A SWITCH MATRIX AND SWITCH SENSING**

Commissioner for Patents
Washington, D.C. 20231

**INFORMATION DISCLOSURE STATEMENT
UNDER 37 C.F.R. §1.97(b)**

In accordance with the duty of disclosure set forth in 37 C.F.R. §1.56,
Applicant(s) hereby submits the following information in conformance with 37 C.F.R.
§§1.97 and 1.98.

- ☒ Pursuant to 37 C.F.R. §1.98, a copy of each document cited in the attached Form PTO/SB/08 is enclosed.
- ☐ No copies of the publications listed on the attached Form PTO/SB/08A are being provided pursuant to 37 C.F.R. §1.98(d) because the publications were previously cited by or submitted to the Office in prior Application Serial No. ___ to which the above-identified application claims priority under 35 U.S.C. §120.
- ☐ Publication(s) ___ listed on the attached Form PTO/SB/08A were cited in a foreign search or examination report corresponding to ___ application serial no. ___ and mailed on ___.
- ☐ Enclosed is a copy of a non-English publication(s) ___. Pursuant to §609 of the M.P.E.P., Applicant submits the attached foreign search or examination report, which cites such non-English language publication(s).
- ☐ Enclosed is a copy of a non-English publication(s) ___. English language publication ___ (copy enclosed) claims priority from this non-English publication.
- ☐ Enclosed is an explanation of non-English publication(s) ___ for which an English translation is not available.

☐ Enclosed is an English translation of non-English publication(s) ___ cited in the attached Form PTO/SB/08A.

☐ Enclosed are copies of pending patent application serial nos.

This Information Disclosure Statement is filed within any one of the following time periods:

☐ within three months from the filing date of this national application other than a CPA under 37 C.F.R. § 1.53(d);

☐ within three months from the date of entry of the national stage as set forth in 37 C.F.R. §1.491 in this international application;

☒ before the mailing date of a first office action on the merits; or

☐ before the mailing of a first office action after the filing of a request for continued examination under 37 C.F.R. § 1.114.

It is respectfully requested that the Examiner consider the above-noted information and return an initialed copy of the attached Form PTO/SB/08A to the undersigned.

Dated: September 27, 2002

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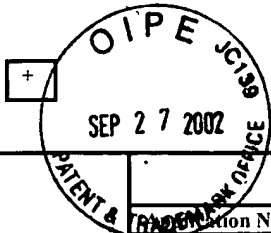
Respectfully submitted,
COOLEY GODWARD LLP

By:



Christopher R. Hutter
Reg. No. 41,087

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PTO/SB/08A (08-00)

Substitute for form 1449A/PTO			Complete if Known	
INFORMATION DISCLOSURE STATEMENT BY APPLICANT (use as many sheets as necessary)			Application Number	09/957,004
			Filing Date	September 19, 2001
			First Named Inventor	Kollin Tierling
			Group Art Unit	2661
			Examiner Name	Unassigned
Sheet 1 of 3	Attorney Docket Number		IMMR-005/00US	

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U.S. PATENT DOCUMENTS					
Examiner Initials*	Cite No. ¹	U.S. Patent Document		Name of Patentee or Applicant of Cited Document	Date of Publication of Cited Document MM-DD-YYYY
		Number	Kind Code ² (if known)		
	A1	5,785,630		Bobick, et al.	07/28/1998
	A2	5,766,016		Sinclair et al.	06/16/1998
	A3	5,547,382		Yamasaki et al.	08/20/1996
	A4	5,466,213		Hogan et al.	11/14/1995
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Examiner Initials*	Cite No. ¹	Foreign Patent Document			Name of Patentee or Applicant of Cited Document	Date of Publication of Cited Document MM-DD-YYYY
		Office ³	Number ⁴	Kind Code ⁵ (if known)		
	B1		0 349 086	A1	Stork Kwant B.V.	01/03/1990
	B2					

¹ Unique citation designation number.

² See attached Kinds of U.S. Patent Documents.

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⁴ For Japanese patent documents, the indication of the year of the reign of the Emperor must precede the serial number of the patent document.

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First Named Inventor Kollin Tierling

Group Art Unit 2661

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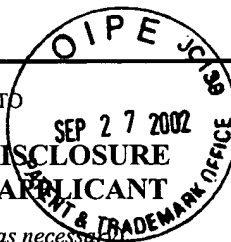
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OTHER PRIOR ART – NON PATENT LITERATURE DOCUMENTS

Examiner Initials*	Cite No. ¹	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published.	T ²
	C1	Baigrie, "Electric Control Loading – A Low Cost, High Performance Alternative," <i>Proceedings of Interservice/Industry Training Systems Conference</i> , pp. 247-254, November 6-8, 1990	
	C2	Iwata, "Pen-based Haptic Virtual Environment," 0-7803-1363-1/93 IEEE, pp. 287-292, 1993	
	C3	Russo, "The Design and Implementation of a Three Degree of Freedom Force Output Joystick," <i>MIT Libraries Archives</i> pp. 1-131, May 1990, archived 8/14/90	
	C4	Brooks et al., "Hand Controllers for Teleoperation - A State-of-the-Art Technology Survey and Evaluation," <i>JPL Publication 85-11</i> , NASA-CR-175890; N85-28559, pp. 1-84, 03/1/1985	
	C5	Jones et al., "A perceptual analysis of stiffness," ISSN 0014-4819 Springer International (Springer-Verlag); <i>Experimental Brain Research</i> , Vol. 79, No. 1, pp. 150-156, 1990	
	C6	Burdea et al., "Distributed Virtual Force Feedback, Lecture Notes for Workshop on Force Display in Virtual Environments and its Application to Robotic Teleoperation," <i>1993 IEEE International Conference on Robotics and Automation</i> , pp. 25-44, 05/02/1993	
	C7	Snow et al., "Model-X Force-Reflecting-Hand-Controller," NT Control No. NPO-17851; JPL Case No. 7348, pp. 1-4 with 45 pages of attachments, 06/15/1989	
	C8	Ouh-Young, "Force Display in Molecular Docking," Doctoral Dissertation, University of North Carolina at Chapel Hill, UMI Order No. 9034744, p. 1-369, 1990	
	C9	Tadros, "Control System Design for a Three Degree of Freedom Virtual Environment Simulator Using Motor/Brake Pair Actuators," <i>MIT Archive</i> , pp. 1-88, February 1990, archived 8/13/90	
	C10	Caldwell et al., "Enhanced Tactile Feedback (Tele-Taction) Using a Multi-Functional Sensory System," 1050-4729/93, pp. 955-960, 1993	
	C11	Adelstein et al., "Design and Implementation of a Force Reflecting Manipulandum for Manual Control research," DSC-Vol. 42, <i>Advances in Robotics</i> , pp. 1-12, 1992	
	C12	Gotow et al., "Controlled Impedance Test Apparatus for Studying Human Interpretation of Kinesthetic Feedback," WA11-11:00, pp. 332-337	
	C13	Stanley et al., "Computer Simulation of Interacting Dynamic Mechanical Systems Using Distributed Memory Parallel Processors," DSC-Vol. 42, <i>Advances in Robotics</i> , pp. 55-61, ASME 1992	
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	C15	Kontarinis et al., "Display of High-Frequency Tactile Information to Teleoperators," <i>Telemanipulator Technology and Space Telerobotics</i> , Won S. Kim, Editor, Proc. SPIE Vol. 2057, pp. 40-50, Sep. 7-9, 1993	
	C16	Patrick et al., "Design and Testing of A Non-reactive, Fingertip, Tactile Display for Interaction with Remote Environments," <i>Cooperative Intelligent Robotics in Space</i> , Rui J. deFigueiredo et al, Editor, Proc. SPIE Vol. 1387, pp. 215-222, 1990	
	C17	Adelstein, "A Virtual Environment System For The Study of Human Arm Tremor," <i>Ph.D. Dissertation</i> , Dept. of Mechanical Engineering, MIT, June 1989, archived 3/13/90	
	C18	Bejczy, "Sensors, Controls, and Man-Machine Interface for Advanced Teleoperation," <i>Science</i> , Vol. 208, No. 4450, pp. 1327-1335, 1980	
	C19	Bejczy et al., "Generalization of Bilateral Force-Reflecting Control of Manipulators," <i>Proceedings Of Fourth CISM-IFTOMM</i> , Sep. 8-12, 1981	
	C20	McAfee et al., "Teleoperator Subsystem/Telerobot Demonstrator: Force Reflecting Hand Controller Equipment Manual," <i>JPL 1988</i> , JPL D-5172	
	C21	Minsky, "Computational Haptics: The Sandpaper System for Synthesizing Texture for a Force-Feedback Display," <i>Ph.D. Dissertation</i> , MIT, June 1995, archived 7/6/95	
	C22	Jacobsen et al., "High Performance, Dextrous Telerobotic Manipulator With Force Reflection," <i>Intervention/ROV '91 Conference & Exposition</i> , Hollywood, Florida, May 21-23, 1991	
	C23	Shimoga, "Finger Force and Touch Feedback Issues in Dexterous Telemanipulation," <i>Proceedings of Fourth Annual Conference on Intelligent Robotic Systems for Space Exploration</i> , Rensselaer Polytechnic Institute, Sep. 30- Oct. 1, 1992	
	C24	IBM Technical Disclosure Bulletin, "Mouse Ball-Actuating Device With Force and Tactile Feedback," Vol. 32, No. 9B, February 1990	
	C25	Terry et al., "Tactile Feedback In A Computer Mouse," <i>Proceedings of Fourteenth Annual Northeast Bioengineering Conference</i> , University of New Hampshire, March 10-11, 1988	
	C26	Howe, "A Force-Relating Teleoperated Hand System for the Study of Tactile Sensing in Precision Manipulation," <i>Proceedings of the 1992 IEEE International Conference on Robotics and Automation</i> , Nice, France, May 1992	
	C27	Eberhardt et al., "OMAR - A Haptic display for speech perception by deaf and deaf-blind individuals," <i>IEEE Virtual Reality Annual International Symposium</i> , Seattle, WA, Sep. 18-22, 1993	

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C28	Rabinowitz et al., "Multidimensional tactile displays: Identification of vibratory intensity, frequency, and contractor area," <i>Journal of The Acoustical Society of America</i> , Vol. 82, No. 4, October 1987	
C29	Bejczy et al., "Kinesthetic Coupling Between Operator and Remote Manipulator," <i>International Computer Technology Conference, The American Society of Mechanical Engineers</i> , San Francisco, CA, August 12-15, 1980	
C30	Bejczy et al., "A Laboratory Breadboard System For Dual-Arm Teleoperation," <i>SOAR '89 Workshop, JSC</i> , Houston, TX, July 25-27, 1989	
C31	Ouhyoung et al., "A Low-Cost Force Feedback Joystick and Its Use in PC Video Games," <i>IEEE Transactions on Consumer Electronics</i> , Vol. 41, No. 3, August 1995	
C32	Marcus, "Touch Feedback in Surgery," <i>Proceedings of Virtual Reality and Medicine The Cutting Edge</i> , Sep. 8-11, 1994	
C33	Bejczy, et al., "Universal Computer Control System (UCCS) For Space Telerobots," CH2413-3/87/0000/0318501.00 1987 IEEE, 1987	

*EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.

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